FINN RIETZ

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OBJECTIVE

Computer Science Master student with 4+ years programming experience in academia and industry seeking Deep Learning Ph.D. positions.

EDUCATION

Master of Science: Computer Science, University of Hamburg

2019 - ongoing

Relevant courses: Bio-Inspired AI, Neural Networks, Machine Learning, Computer Vision, Intelligent Robotics

Current GPA: 1.1

Bachelor of Science: Human-Computer Interaction, University of Hamburg

2015 - 2019

Relevant courses: Software Engineering, Databases, Statistics, General & Developmental Psychology

TECHNICAL SKILLS

Languages Frameworks

Others

Python, Java, C#, Javascript, SQL, Bash, PHP, ABAP, Dart, HTML, CSS

PyTorch/Tensorflow, Matplotlib, Pandas, Flask, JQuery, SAPUI5, Flutter, NAOqi OS & API

Git, ROS, Docker, Debian Linux, Unity, Raspberry Pi, Softbank's Pepper

EXPERIENCE

Student assistant

Jul 2019 - ongoing

Knowledge Technology Research Group

Hamburg, Germany

- Implemented various applications on Pepper Robots, including:
 - Extensive work on Simultaneous Localization and Mapping for office navigation
 - ROS architecture for demonstration of internal projects
- Tutor for Cognitive Robotics Project 2020, 2021
- Webmaster for KT Group's Website

Machine Learning Expert

nextMedia.Hamburg

Nov 2019 - Jan 2020

Hamburg, Germany

- Three months stipend for prototyping NLP solutions at DER SPIEGEL
- Successfully developed an N-Gram classification model for malicious advertisements, in collaboration with Google Germany

Student employee: Fullstack SAP

Otto Group IT

Feb 2017 - Jun 2019 Hamburg, Germany

- Developed OData SAPUI5 customer feedback Web-app
- Developed SAP based anonymization pipeline for training data collection
- Build physical and software solution for always-on SCRUM board

EXTRA-CIRRUCULAR ACTIVITIES

Visiting Researcher

Sep 2020 - Dez 2020

Umeå, Sweden

Intelligent Robotics Research Group

- Three months stipend for developing a WoZ Interface for Pepper robot
- Presented outcome at 2020 Workshop on Affective Shared Perception
- Paper accepted in Frontiers in Robotics and AI: Human-Robot Interaction: Technology and Code